Environmental Multiway Data Mining



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Acknowledgements







Introduction

- Some environmental multiway data
- Canonical Polyadic Decomposition
- Challenges in environmental data mining
- Compressed Constrained CPD
- 3 Multiway Data Fusion
 - Ourrent Works



Hyperspectral imaging principle



- Each image is a **mixture** of various materials.
- Each material has a unique spectral response.

Credits for illustrations : Veganzones(left) and Bioucas(right)



Snow in the Alps [Veganzones,2015]



 $\overbrace{\mathsf{Fold}\ 1\mathsf{D} \leftarrow 2\mathsf{D}}^{\mathsf{Fold}\ 1\mathsf{D}}$



Snow in the Alps [Veganzones, 2015]



Snow in the Alps [Veganzones, 2015]



Pixels

Snow in the Alps [Veganzones, 2015]

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Another example : Fluorescence Spectroscopy



Fluorescence Spectroscopy Data



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Fluorescence Spectroscopy Data



- Multiway arrays (tensors) appear naturally in data processing.
- Data are mixtures of signals unique to each material or chemical.

Main Issue : unmixing the data

How to extract meaningful information from multiway data?



Unmixed data = rank 1 tensors

In some cases, meaningful information is contained in ${\bf simpler}$ tensors i.e. rank 1 tensors :



Main tool : Canonical Polyadic Decomposition

Canonical Polyadic Decomposition [Hitchcock, 1927] aims at extracting all R components.



- Unmixing does not require additional knowledge
- Not applicable for 2-way arrays

Challenges in environmental and biomedical data mining

• Constrained Decompositions - Compressed Decompositions \rightarrow Nonnegative Large tensor

Challenges in environmental and biomedical data mining

• Constrained Decompositions - Compressed Decompositions \rightarrow Nonnegative Large tensor

• Data Fusion







2 Compressed Constrained CPD
 • Some definitions and properties
 • Compressed-based CPD
 • Nonnegative CPD

3 Multiway Data Fusion

Current Works



Some notations



 $\begin{array}{ll} \boldsymbol{\mathcal{T}} \text{ has sizes } K \times L \times M \\ \otimes \text{ is the tensor product} \end{array} \quad \begin{array}{l} \mathbf{A} = [\mathbf{a}_1, \dots, \mathbf{a}_R] \text{ has sizes } K \times R \\ \bullet_i \text{ is the contraction on mode } i \end{array} \\ R \text{ is the rank of } \boldsymbol{\mathcal{T}}, \text{ i.e. smallest number of rank-one tensors spanning } \boldsymbol{\mathcal{T}}. \end{array}$

Some definitions and properties : multilinear transformation

Definition (Orthogonal Tucker Decomposition)

A tensor $\mathcal{T} \in \mathbb{R}^K \otimes \mathbb{R}^L \otimes \mathbb{R}^M$ can be expressed in an orthonormal basis $\mathbf{U} \otimes \mathbf{V} \otimes \mathbf{W}$ so that

 $\mathcal{T} = (\mathsf{U} \otimes \mathsf{V} \otimes \mathsf{W}) \, \mathcal{G}$

where $\mathbf{U} \in K \times R_1$, $\mathbf{V} \in L \times R_2$, $\mathbf{W} \in M \times R_3$ and $R_1, R_2, R_3 \leq \operatorname{rank}(\mathcal{T})$.



Tensor compression in the noisy case

In the noisy case : [DeLathauwer,2000] (approximate) truncated HOSVD



where $\hat{\mathbf{U}}\mathbf{N}_1 = TSVD(\mathbf{T}_{(1)})$ $\hat{\mathbf{V}}\mathbf{N}_2 = TSVD(\mathbf{T}_{(2)})$ $\hat{\mathbf{W}}\mathbf{N}_3 = TSVD(\mathbf{T}_{(3)})$

 $\widehat{\mathcal{T}} pprox (\widehat{\mathbf{U}} \otimes \widehat{\mathbf{V}} \otimes \widehat{\mathbf{W}}) \widehat{\mathcal{G}}$ and $\widehat{\mathcal{G}} = (\mathbf{A}_c \otimes \mathbf{B}_c \otimes \mathbf{C}_c) \mathcal{I}_R + \mathcal{E}_c$

Tensor CPD using compression

- **1** Compress \mathcal{T} using any fast HOSVD
- 2 Decompose $\widehat{\mathcal{G}}$ to get $\widehat{\mathbf{A}}_c, \widehat{\mathbf{B}}_c, \widehat{\mathbf{C}}_c$
- **3** Decompress : $\widehat{\mathbf{A}} = \widehat{\mathbf{U}}\widehat{\mathbf{A}}_c, \ \widehat{\mathbf{B}} = \widehat{\mathbf{V}}\widehat{\mathbf{B}}_c, \ \widehat{\mathbf{C}} = \widehat{\mathbf{W}}\widehat{\mathbf{C}}_c$

Time in seconds for CP dec. $N \times N \times N$ - rank 5 random tensor :

Ν	10	50	100	200	300
Alternating Least Squares (ALS)	0.36	0.70	1.92	7.13	26.43
Compressed ALS	0.33	0.39	0.45	0.93	2.14

Nonnegativity constraints



In many applications : $\boldsymbol{A}, \boldsymbol{B}, \boldsymbol{C} \geqslant \boldsymbol{0}$

Compressed Nonnegative CPD :

$$\begin{array}{ll} \min_{\mathbf{A}_{c},\mathbf{B}_{c},\mathbf{C}_{c}} & \|\widehat{\boldsymbol{\mathcal{G}}}-(\mathbf{A}_{c}\otimes\mathbf{B}_{c}\otimes\mathbf{C}_{c})\boldsymbol{\mathcal{I}}_{R}\|_{F}^{2}\\ \text{sub. to} & \widehat{\mathbf{U}}\mathbf{A}_{c},\widehat{\mathbf{V}}\mathbf{B}_{c},\widehat{\mathbf{W}}\mathbf{C}_{c} \geq 0 \end{array}$$

Issue : Difficult exact projection on $\widehat{\mathbf{U}}\mathbf{A}_c \ge 0$

The uncompressed projective algorithm : ANLS

The cost function is minimized with respect to each factor alternatively :

$$\begin{array}{ll} \min_{\mathbf{A}} & \| \boldsymbol{\mathcal{T}} - (\mathbf{A} \otimes \mathbf{B} \otimes \mathbf{C}) \boldsymbol{\mathcal{I}}_{R} \|_{F}^{2} \\ \text{sub. to} & \mathbf{A} \geq 0 \end{array}$$

First, the unconstrained least squares update is computed :

$$\widehat{\mathsf{A}} = \mathsf{T}_1 \left(\mathsf{B} \odot \mathsf{C}
ight)^\dagger$$

Then the least squares estimate is projected on the constraint space :

$$\widehat{\mathsf{A}} = \left[\widehat{\mathsf{A}}\right]^+$$

Approximate projection and PROCO-ALS

Approximate projection Π :

Given Least Squares update $\widehat{\mathbf{A}}_c$

Decompression : Â := ÛÂ_c
Projection : Â := [Â]⁺
Compression : Â_c := Û^TÂ

 $\mathbf{\Pi}\left[\widehat{\mathbf{A}}\right] = \mathbf{U}^{\mathsf{T}}\left[\mathbf{U}\mathbf{A}_{c}\right]^{+}$

Projected and compressed framework (PROCO) [Cohen, 2014]

Other possible algorithms and related problems

• PROCO-ALS [Cohen,2014], Compressed-AOADMM [Cohen,2016]

$$\begin{array}{l} \text{minimize } \|\widehat{\boldsymbol{\mathcal{G}}} - (\boldsymbol{A}_c \otimes \boldsymbol{B}_c \otimes \boldsymbol{C}_c) \boldsymbol{\mathcal{I}}_R\|_F^2 \\ \text{w.r.t. } \boldsymbol{A}_c, \boldsymbol{B}_c, \boldsymbol{C}_c \\ \text{s.t. } \widehat{\boldsymbol{U}}\boldsymbol{A}_c \succeq \boldsymbol{0} \end{array}$$

• Tensorlab 3.0 [Vervliet,2016]

$$\begin{array}{l} \mbox{minimize} & \| \left(\widehat{\boldsymbol{\mathsf{U}}} \otimes \widehat{\boldsymbol{\mathsf{V}}} \otimes \widehat{\boldsymbol{\mathsf{W}}} \right) \widehat{\boldsymbol{\mathcal{G}}} - \left(\boldsymbol{\mathsf{A}} \otimes \boldsymbol{\mathsf{B}} \otimes \boldsymbol{\mathsf{C}} \right) \boldsymbol{\mathcal{I}}_{\mathcal{R}} \|_{F}^{2} \\ \mbox{w.r.t.} \ \boldsymbol{\mathsf{A}}, \boldsymbol{\mathsf{B}}, \boldsymbol{\mathsf{C}} \\ \mbox{s.t.} \ \boldsymbol{\mathsf{A}} \succeq \boldsymbol{\mathsf{0}} \end{array}$$

• AOADMM [Huang, 2015], FastNNLS [Bro, 1997], ANLS

minimize
$$\| \boldsymbol{\mathcal{T}} - (\mathbf{A} \otimes \mathbf{B} \otimes \mathbf{C}) \boldsymbol{\mathcal{I}}_R \|_F^2$$

w.r.t. $\mathbf{A}, \mathbf{B}, \mathbf{C}$
s.t. $\mathbf{A} \succeq 0$

Simulated Data



Size : $100 \times 100 \times 100$ Rank : 5 Gaussian factors R_i : $5 \times 5 \times 5$ SNR : 30dB Gaussian i.i.d. noise

Experimental Data : Fluorescence Spectroscopy

Fluorescence spectroscopy data :

excitation spectra emission spectra mixtures

multimodal chemometrics data set from [Acar,2013]

Description

5 compounds : Valine-Tyrosine-Valine (Val), Tryptophan- Glycine (Gly), Phenylalanine (Phe), Maltoheptaose (Mal) and Propanol (Pro)

Nb. of excitation wave lengths21 (A)Nb. of emission wave lengths251 (B)Nb. of Mixtures28 (C)Missing values30% (replaced by zeros)

Experimental data : Results



Introduction

2 Compressed Constrained CPD

3 Multiway Data Fusion

- Problem statement
- Flexible data fusion
- Experiments

Current Works



Direct coupling [Harshman, 1984]



Example : Fluorescence spectroscopy data and Nuclear Magnetic Resonance data

Direct coupling (2)

$$\forall i \in [1, N], \begin{cases} \mathcal{T}_i = (\mathbf{A}_i \otimes \mathbf{B}_i \otimes \mathbf{C}_i) \mathcal{I}_R + \mathcal{E}_i \\ \mathbf{C}_i = \mathbf{C}^* \end{cases}$$

If the noises \mathcal{E}_i are Gaussian with i.i.d. entries, then the Maximum Likelihood Estimator (MLE) of the factors is

$$\underset{\mathbf{A}_{i},\mathbf{B}_{i},\mathbf{C}}{\operatorname{argmin}}\sum_{i=1}^{N}\|\boldsymbol{\mathcal{T}}_{i}-(\mathbf{A}_{i}\otimes\mathbf{B}_{i}\otimes\mathbf{C}^{*})\boldsymbol{\mathcal{I}}_{R}\|_{F}^{2}$$

For computation,

- CMTF by Acar et al.
- ALS by Cabral Farias, Cohen et al. (Tensor Package)
- Tensorlab 3.0 by Vervliet et al.

Problem statement

Other coupling models

• Parafac 2 [Harshman,1972] :

$$\forall i \in [1, N], \begin{cases} \mathcal{T}_i = (\mathbf{A} \otimes \mathbf{B} \otimes \mathbf{C}_i) \mathbf{\Sigma}_{iR} + \mathcal{E}_i \\ \mathbf{C}_i = \mathbf{P}_i \mathbf{C}^* \\ \mathbf{P}_i^{\mathsf{T}} \mathbf{P}_i = \mathbf{I} \end{cases}$$

• Shift Parafac [Harshman,2003] :

$$\forall i \in [1, N], \begin{cases} \mathbf{M}_i = (\mathbf{A} \otimes \mathbf{B}_i) \mathbf{\Sigma}_{iR} + \mathbf{E}_i \\ \mathbf{b}_r^{(i)} = \tau^{\delta_{ir}}(\mathbf{b}_r^*) \end{cases}$$

Problem statement

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$$\forall i \in [1, N], \begin{cases} \mathbf{M}_i = (\mathbf{A} \otimes \mathbf{B}_i) \, \mathbf{\Sigma}_{iR} + \mathbf{E}_i \\ \mathbf{b}_r^{(i)} = \tau^{\delta_{ir}}(\mathbf{b}_r^*) \end{cases}$$

A more general framework?

General Framework using a Bayesian approach [Cabral Farias, Cohen,2015]

• Parameters
$$\boldsymbol{\theta}_i = \begin{bmatrix} \operatorname{vec}(\mathbf{A}_i) \\ \operatorname{vec}(\mathbf{B}_i) \\ \operatorname{vec}(\mathbf{C}_i) \end{bmatrix}$$
 are random

• Known prior distribution $p(\theta_1, \ldots, \theta_N)$ and likelihoods $p(\mathcal{Y}_i | \theta_i)$

MAP estimation under conditionnal independance

 $\underset{\theta_1,\ldots,\theta_N}{\arg \max} p(\theta_1,\ldots,\theta_N | \mathcal{Y}_1,\ldots,\mathcal{Y}_N) = \underset{\theta_1,\ldots,\theta_N}{\arg \min} \Upsilon(\theta_1,\ldots,\theta_N)$

$$\begin{aligned} \Upsilon(\boldsymbol{\theta}_1, \dots, \boldsymbol{\theta}_N) &= -\sum_{i=1}^N \log p(\mathcal{Y}_i | \boldsymbol{\theta}_i) - \log p(\boldsymbol{\theta}_1, \dots, \boldsymbol{\theta}_N) \\ &= \text{ data fitting terms } + \text{ coupling} \end{aligned}$$

Examples of flexible coupling models

Noisy exact coupling on C_i

$$\forall i \in [1, N], \begin{cases} \mathcal{T}_i = (\mathbf{A}_i \otimes \mathbf{B}_i \otimes \mathbf{C}_i) \mathcal{I}_R + \mathcal{E}_i \\ \mathbf{C}_i = \mathbf{C}^* + \mathbf{\Gamma}_i \\ \mathbf{\Gamma}_i \sim \mathcal{AN}\left(\mathbf{0}, \frac{1}{\sigma_{c,i}^2} \mathbf{I} \otimes \mathbf{I}\right) \end{cases}$$

$$\Upsilon(\boldsymbol{\theta}_1,\ldots,\boldsymbol{\theta}_N,\mathbf{C}^*) = -\sum_{i=1}^N \frac{1}{\sigma_1^2} \|\boldsymbol{\mathcal{T}}_i - (\mathbf{A}_i \otimes \mathbf{B}_i \otimes \mathbf{C}_i)\boldsymbol{\mathcal{I}}_R\|_F^2 - \sum_{i=1}^N \frac{1}{\sigma_{ci}^2} \|\mathbf{C}_i - \mathbf{C}^*\|_F^2$$

Examples of flexible coupling models

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Linear coupling on **C**_i

$$\forall i \in [1, N], \begin{cases} \mathcal{T}_i = (\mathbf{A}_i \otimes \mathbf{B}_i \otimes \mathbf{C}_i) \mathcal{I}_R + \mathcal{E}_i \\ \mathbf{H}_i \mathbf{C}_i = \mathbf{H}_j \mathbf{C}_j + \mathbf{\Gamma}_{ij} \\ \mathbf{\Gamma}_{ij} \sim \mathcal{AN}\left(\mathbf{0}, \frac{1}{\sigma_{ij}^2} \mathbf{I} \otimes \mathbf{I}\right) \end{cases}$$

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Elexible data fusion

Optimization Strategies

Alternating Least Squares (ALS) based methods

- Fast
- Simple to implement
- Tackle various coupling models
- Require warm initialization
- Unadapted for non-Gaussian distributions

Second-order methods (Tensorlab 3.0)

- Tackle a wide variety of models and noise distributions
- Not very sensitive to initialization
- Slow

Simulation : Resampling Bandlimited Signals





Simulation : Resampling Bandlimited Signals



Total MSE on the continuous functions (numerical integration)

	C ₁ Shannon	C ₂ noisy
Uncoupled	33.4968	2.6581
Coupled	33.4968	1.0375

Experiments

Experimental Data : NMR

Nuclear magnetic resonance data : diamited for the second second

same sample presented previously : coupling through C

Nb. of chemical shifts13324 (A')Nb. of gradient levels8 (B')Nb. of Mixtures28 (C)Missing values0% (replaced by zeros)

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Results : Relative Concentrations of Phenylalanine



Introduction

- 2 Compressed Constrained CPD
- 3 Multiway Data Fusion

4 Current Works



Joint Compression





Current Works

Dictionary-based CPD : Linear and Sparsity constraints



Introduction

- 2 Compressed Constrained CPD
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4 Current Works



Conclusions

- Fast algorithm PROCO-ALS for constrained decompositions when projection is available. Need more theoretical results.
- Data fusion framework, first step towards non-trivial coupling models. More experimental data required.
- Among other research topics covered during the PhD : non-linear fluorescence tensor decomposition, notations, data fusion for Gaze-EEG data.

Selected list of publications

- J. E. Cohen, P. Comon, and X. Luciani, "Correcting inner filter effects, a non multilinear tensor decomposition method," *Chemometrics and Intelligent Laboratory Systems*, vol. 150, pp. 29–40, 2016.
- M. A. Veganzones, J. E. Cohen, R. Cabral Farias, J. Chanussot, and P. Comon, "Nonnegative tensor CP decomposition of hyperspectral data," *IEEE Transactions* on Geoscience and Remote Sensing, Nov. 2015.
- J. E. Cohen, R. C. Farias, and P. Comon, "Fast decomposition of large nonnegative tensors," *IEEE Signal Processing Letters*, vol. 22, no. 7, pp. 862–866, 2015.
- R. Cabral Farias, J. E. Cohen, C. Jutten, and P. Comon, "Joint decompositions with flexible couplings," in 12th International Conference on Latent Variable Analysis and Signal Separation (LVA/ICA), (Liberec, Czech Republic), Aug. 2015.

Thank you for your attention !



Rank and minimum compressed dimensions



Exproratory : it suggests a Rank 2 or 3 : Mal and Pro are not fluorescent

Modeling

$$\begin{array}{l} \mathcal{T}_{EEM} = (\mathbf{A}_{EEM} \otimes \mathbf{B}_{EEM} \mathbf{C}_{EEM}) \mathcal{I}_{3} + \mathcal{E}_{EEM} \\ \mathcal{T}_{NMR} = (\mathbf{A}_{NMR} \otimes \mathbf{B}_{NMR} \mathbf{C}_{NMR}) \mathcal{I}_{5} + \mathcal{E}_{NMR} \\ \mathbf{C}_{EEM} = \mathbf{C}_{NMR} (r = 1, 2, 3) + \mathbf{\Gamma}_{c} \\ \|\mathbf{c}_{i}^{EEM}\|_{1} = 1 \ \forall i \leq 3 \\ \mathcal{E}_{EEM} \sim \mathcal{AN} \left(\mathbf{0}, \mathbf{I}_{21} \otimes \mathbf{I}_{251} \otimes \mathbf{I}_{28} \right) \\ \mathcal{E}_{NMR} \sim \mathcal{AN} \left(\mathbf{0}, \frac{1}{\sigma_{MMR}^{2}} \mathbf{I}_{8} \otimes \mathbf{I}_{13324} \otimes \mathbf{I}_{28} \right) \\ \mathbf{\Gamma}_{c} \sim \mathcal{AN} \left(\mathbf{0}, \frac{1}{\sigma_{c}^{2}} \mathbf{I}_{28} \otimes \mathbf{I}_{3} \right) \end{array}$$

Challenges in environmental data mining

Constrained Compression

$$\begin{cases} \mathcal{G} = (\mathsf{A}_c \otimes \mathsf{B}_c \otimes \mathsf{C}_c) \mathcal{I}_R + \mathcal{E}_c \\ \mathsf{WC}_c \in \mathcal{S}_C \end{cases}$$

Multiway Data Fusion

$$\begin{array}{l} \mathcal{T}_{i} &= (\mathbf{A}_{i} \otimes \mathbf{B}_{i} \otimes \mathbf{C}_{i}) \mathcal{I}_{R_{i}} + \mathcal{E}_{i} \\ \mathbf{A}_{i} &= f_{i}^{(\mathbf{A})}(\mathbf{A}^{*}), \quad f_{i}^{(\mathbf{A})} \in \mathcal{F}^{(\mathbf{A})} \\ \mathbf{B}_{i} &= f_{i}^{(\mathbf{B})}(\mathbf{B}^{*}), \quad f_{i}^{(\mathbf{B})} \in \mathcal{F}^{(\mathbf{B})} \\ \mathbf{C}_{i} &= f_{i}^{(\mathbf{C})}(\mathbf{C}^{*}), \quad f_{i}^{(\mathbf{C})} \in \mathcal{F}^{(\mathbf{C})} \end{array}$$

Some definitions and properties : tensor space and rank

Definition (Tensor space)

A tensor space $\mathcal{E} \otimes \mathcal{F}$ is the linear space obtained by mapping all bilinear maps on $\mathcal{E} \times \mathcal{F}$ to linear maps. It is unique up to isomorphisms.

Definition (Tensor and rank)

A real valued tensor \mathcal{T} is a vector of a tensor space $(\mathbb{R}^K \otimes \mathbb{R}^L \otimes \mathbb{R}^M, \otimes)$. The rank of \mathcal{T} is the minimal number of elements $\mathbf{a} \otimes \mathbf{b} \otimes \mathbf{c}$ needed to express \mathcal{T} . A tensor can be considered low rank when R is much smaller than the dimensions K, L, M.

When the tensor product \otimes is cast as the outer product \circ , tensors can be considered as multiway arrays without loss of generality.

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Results : Emission spectra and chemical shifts



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